Double-Exponential Fast Gauss Transform Algorithms for Pricing Discrete Lookback Options

By

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Abstract

This paper presents fast and accurate algorithms for computing the prices of discretely sampled lookback options. Under the Black-Scholes framework, the pricing of a discrete lookback option can be reduced to a series of convolutions of a function with the Gaussian distribution. Using this fact, an efficient algorithm, which computes these convolutions by a combination of the double-exponential integration formula and the fast Gauss transform, has been proposed recently. We extend this algorithm to lookback options under Merton’s jump-diffusion model and American lookback options. Numerical experiments show that our method is much faster and more accurate than conventional methods for lookback options under Merton’s model. For American lookback options, our method outperforms conventional methods when required accuracy is relatively high.

§1. Introduction

A lookback option is the right to sell an asset at the end of a time period at the highest price the asset took during the period (lookback put option), or to buy an asset at the lowest price it took during the period (lookback call option). It is one of the most popular exotic options and various types of lookback options are traded in the market. Usually, the maximum or minimum

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is taken over a finite set of time points within the period called monitoring
dates, and such options are called discrete lookback options.

The price of a lookback option is given as the discounted expectation value
of the option payoff under the risk-neutral probability measure \([9]\). In the
case of discrete lookback options, it is difficult to find an explicit formula for
the expectation value and many numerical methods have been proposed so
far, including the Monte Carlo method, the binomial method \([13][14][3][2]\) and
Reiner’s convolution method \([21]\). The binomial method approximates the geo-
metric Brownian motion of the underlying asset by a discrete process on a
lattice. Reiner’s convolution method, on the other hand, exploits the fact that
the expectation value can be computed by a series of convolutions of a function
with the transition probability density function (tpdf) of the asset price, and
computes these convolutions with the fast Fourier transform.

Recently, Broadie and Yamamoto \([8]\) proposed a fast and accurate algo-
rithm for pricing discrete path-dependent options including the lookback op-
tion. Their method is also based on the representation of the expectation value
by a series of convolutions and computes these convolutions efficiently by a
combination of the double-exponential numerical integration formula \([22]\) and
the fast Gauss transform \([11][12][16]\). Numerical experiments show that their
method is much faster and more accurate than conventional methods. How-
ever, their algorithm has been limited to the standard lookback options under
the Black-Scholes model.

In this paper, we generalize their algorithm in two ways. First, we extend
the algorithm to deal with lookback options under Merton’s lognormal jump-
diffusion model \([19]\). This model is important because it can capture the heavy
tails of the tpdf of the asset price, which are often observed in the market
but cannot be described by the Black-Scholes model. Second, we propose a
modified version of the algorithm that can price American lookback options,
a variant of the lookback option with an early exercise feature. We compare
our algorithms with the conventional pricing methods such as the Monte Carlo
method, the binomial method and Reiner’s convolution method and show the
effectiveness of our approach.

This paper is organized as follows. In section 2, we formulate the pricing
problem of lookback options and show how the pricing computation can be
reduced to a series of convolutions. Sections 3 and 4 provide the details of our
algorithms for the standard lookback options under Merton’s jump-diffusion
model and the American lookback options, respectively. Numerical results that
illustrate the performance of our algorithms are shown in section 5. Finally, we
give some concluding remarks in section 6.

\section{Problem formulation}

In this section, we formulate the pricing problem of lookback put options following [8]. The pricing of lookback call options can be done in a completely parallel manner, so we concentrate on put options in the following. Let the time period be \([0, T]\) and the monitoring dates be \(t_i = i\Delta t\) \((i = 0, 1, \ldots, n)\), where \(\Delta t = T/n\). Also, denote the asset price at \(t_i\) by \(S_i\) and let

\[ M_i = \max_{1 \leq k \leq i} S_k. \]

Then the payoff of the lookback put option can be written as \(M_n - S_n\) and its price at time 0 is given by

\[ V^{LP}_0(S_0) = e^{-rT} E_0[M_n - S_n], \]

where \(r\) is the riskless interest rate and \(E_0[\cdot]\) is the conditional expectation value operator under the risk-neutral probability measure \(Q\) given information up to time \(t\) [9].

Eq. (2.2) involves two random variables \(S_n\) and \(M_n\) at time \(T\), so we need the joint distribution function of them to compute the expectation value. To reduce the dimensionality of the problem, we apply a change of measure (see Babbs [2] and Andreasen [1]) and rewrite eq. (2.2) as:

\[ V^{LP}_0(S_0) = e^{-qT} S_0 E'_0 \left[ \frac{M_n}{S_n} - 1 \right], \]

where \(q\) is the dividend rate and \(E'_0[\cdot]\) denotes the conditional expectation operator under a new measure \(Q'\) defined by

\[ dQ' = \frac{S_n}{S_t e^{(r-q)(T-t)}} dQ. \]

By further introducing the log stock prices \(s_i = \ln(S_i/S_0)\) and \(m_i = \ln(M_i/S_0)\), we can finally write the option price as

\[ V^{LP}_0(S_0) = e^{-qT} S_0 E'_0 \left[ e^{m_n - s_n} - 1 \right]. \]

This shows that it is sufficient to find the distribution of \(m_n - s_n\) to compute the option price.

To compute eq. (2.5), we consider the distribution of \(m_i - s_i\) \((i = 0, 1, \ldots, n)\). Apparently, the distribution function is zero when \(m_i - s_i < 0\) and there is a
finite probability mass at \( m_i - s_i = 0 \). We therefore represent the distribution of \( m_i - s_i \) by two quantities, namely, a scalar \( c_i \) which represents the probability that \( m_i - s_i = 0 \) and a function \( g_i(x) \) \( (x > 0) \) which represents the probability density in the region \( m_i - s_i > 0 \). Note that the probability density function (pdf) of \( m_i - s_i \) can be formally written as \( c_i \delta(x) + g_i(x) \), where \( \delta(x) \) is the Dirac delta function. At time 0, we have

\[
(2.6) \quad c_0 = 1 \quad \text{and} \\
(2.7) \quad g_0(x) = 0
\]

by definition. To compute \( c_i \) and \( g_i(x) \) given \( c_{i-1} \) and \( g_{i-1}(x) \), we use the identity:

\[
(2.8) \quad m_i - s_i = \max(0, m_{i-1} - s_i) = \max(0, (m_{i-1} - s_{i-1}) + (s_{i-1} - s_i)).
\]

If the asset price follows a Levy process, as in the case of the Black-Scholes model or Merton’s jump-diffusion model, the increment \( s_{i-1} - s_i \) is independent of \( m_{i-1} - s_{i-1} \) and eq. (2.8) suggests that the pdf of \( m_i - s_i \) is obtained by computing the convolution of the pdf of \( m_{i-1} - s_{i-1} \) with that of \( s_{i-1} - s_i \) and collecting all the probability mass corresponding to \( m_i - s_i < 0 \) to the point \( m_i - s_i = 0 \). In summary, we have the following recursion formula:

\[
(2.9) \quad \tilde{g}_i(x) = \int_{-\infty}^{\infty} \left\{ c_{i-1} \delta(y) + g_{i-1}(y) \right\} f(x - y) dy \\
= c_{i-1} f(x) + \int_{0}^{\infty} g_{i-1}(y)f(x - y) \, dy, \\
(2.10) \quad c_i = \int_{-\infty}^{0} \tilde{g}_i(x), \\
(2.11) \quad g_i(x) = \tilde{g}_i(x) \quad (x > 0),
\]

where \( f(x) \) is the probability density function of \( s_{i-1} - s_i \). Equations (2.6), (2.7), (2.9), (2.10) and (2.11), along with eq. (2.5), provides us with a means of computing the lookback option price by a series of convolutions.

\section{The DE-FGT algorithm for pricing lookback options under Merton’s jump-diffusion model}

\textbf{The model} Now we consider the case where the asset price follows the log-normal jump-diffusion model introduced by Merton [19]. Under the probability
measure $Q$, the dynamics of $S_t$ is governed by the following equation:

$$dS_t/S_t = (r - q - \nu \lambda)dt + \sigma dW_t + d\left(\sum_{i=1}^{N^0(t)} (J_i - 1)\right),$$

(3.1)

where $W_t$ is a Wiener process, $N^0(s)$ is the number of jumps between $t$ and $t + s$, which follows a Poisson process with intensity $\lambda$, $\{J_i\}$ is a sequence of i.i.d. random variables whose distribution is given by

$$\ln(1 + J_i) \sim N(\gamma - \frac{1}{2} \delta^2, \delta^2),$$

(3.2)

$$\nu = e^\gamma - 1, \quad \text{and}$$

(3.3)

$$S_{t-} = \lim_{s \to t-} S_s.$$  

(3.4)

The constants $\gamma$ and $\delta$ determine the mean and the standard deviation of the jumps, respectively. The processes $W_t$, $N^0(s)$ and $\{J_i\}$ are assumed to be mutually independent. This model is important because it introduces discontinuous changes in the asset price and thereby reproduces the heavy tails of the transition probability function, a characteristic which is often observed in the market but cannot be described by the Black-Scholes model.

In this model, the market becomes incomplete because of the existence of jumps and the standard option pricing argument based on the replicating portfolio [4] is no longer applicable. However, under the assumption that the jump risk is diversifiable, Merton [19] shows that the price can again be written as the discounted expectation value of the option payoff. Thus, the incompleteness of the market causes little problem from the computational point of view.

**Computing the lookback option price by the recursion formula.**

To compute the lookback option price using the recursion formula (2.9), (2.10) and (2.11), we need to know the pdf of $s_{t-1} - s_i$ under the new probability measure $Q'$ defined by eq. (2.4). Andreasen [1] shows that under $Q'$, the asset price $S_t$ follows a new equation:

$$dS_t/S_t = (r - q - \nu \lambda + \sigma^2)dt + \sigma dW'_t + d\left(\sum_{i=1}^{N^0(t)} (J'_i - 1)\right),$$

(3.5)

where $W'_t$ is a Wiener process under $Q'$, $\{J'_i\}$ is a sequence of i.i.d. random variables whose distribution is given by

$$\ln(1 + J'_i) \sim N(\gamma + \frac{1}{2} \delta^2, \delta^2),$$

(3.6)
and \( N^P_i(t) \) is a Poisson process under \( Q' \) with modified intensity

\[
X = \lambda(1 + \nu) = \lambda e^\gamma. \tag{3.7}
\]

Andreasen’s proof is based on Girsanov’s theorem [15][20] for jump-diffusion processes. Alternatively, we can show by elementary arguments that an expectation value of the form:

\[
V_0(S_0) = e^{-rT} E_0[h(S_0, S_1, \ldots, S_n) S_n] \tag{3.8}
\]

can be computed as

\[
V_0(S_0) = e^{-qT} S_0 E'_0[h(S_0, S_1, \ldots, S_n)], \tag{3.9}
\]

where \( E'_0[\cdot] \) denotes the expectation value obtained by assuming that \( S_t \) follows a modified process specified by eqs. (3.5), (3.6) and (3.7). See the appendix for the proof. Because \( M_n \) is a function of \( \{S_0, S_1, \ldots, S_n\} \), we can readily apply this fact to obtain eq. (2.3) from eq. (2.2).

By integrating eq. (3.5), we have

\[
S_i = S_{i-1} \exp \left\{ \left( r - q + \frac{1}{2} \sigma^2 - \nu \lambda \right) \Delta t + \sigma \sqrt{\Delta t} z'_0 + \sum_{l=1}^{N^P_i(\Delta t)} \left( \delta z'_l + \gamma + \frac{1}{2} \delta^2 \right) \right\}, \tag{3.10}
\]

where \( z_l \ (l = 0, 1, \ldots) \) are independent random variables that follow the standard normal distribution \( N(0,1) \) under \( Q' \). Thus we know that the pdf of \( s_{i-1} - s_i \) has the following form:

\[
f(x) = \sum_{l=0}^{\infty} e^{-\lambda \Delta t} \frac{\left( \lambda \Delta t \right)^l}{l!} f^{(l)}(x), \tag{3.11}
\]

where

\[
f^{(l)}(x) = \frac{1}{\sqrt{2\pi} \sigma_l} \exp \left\{ - \frac{(x + \mu'_l)^2}{2 \sigma^2_l} \right\}, \tag{3.12}
\]

\[
\mu'_l = \left( r - q + \frac{1}{2} \sigma^2 - \nu \lambda \right) \Delta t + l \left( \gamma + \frac{1}{2} \delta^2 \right), \quad \text{and} \tag{3.13}
\]

\[
\sigma^2_l = \sigma^2 \Delta t + l \delta^2. \tag{3.14}
\]

By truncating the infinite sum in eq. (3.11) at some \( l_{\text{max}} \) and inserting the result into eq. (2.9), we can express the integral in the recursive formula (2.9)
as a sum of convolutions of \( g_{l-1}(x) \) with Gaussian functions:

\[
I_i(x) \equiv \int_0^\infty g_{l-1}(y)f(x-y)\,dy \\
\simeq \sum_{l=0}^{l_{\text{max}}} e^{-l^2\Delta t} \frac{(N\Delta t)^l}{l!} \int_0^\infty g_{l-1}(y)f^{(l)}(x-y)\,dy.
\]

(3.15)

**Application of the DE-FGT algorithm** Now that the convolution in eq. (2.9) have been decomposed into convolutions of a function with Gaussian distribution, we can apply the Double-Exponential Fast Gauss Transform algorithm proposed in [8]. In particular, we introduce a double-exponential type change of variables:

\[
y = \ln \left\{ 1 + \exp \left( \frac{\pi}{2} (1 + u - e^{-u}) \right) \right\}
\]

(3.16)

and apply it to each term of eq. (3.15), obtaining

\[
I_i^{(l)}(x) = \int_0^\infty g_{l-1}(y)^{(l)}f(x-y)\,dy \\
= \int_{-\infty}^\infty g_{l-1} \left( \ln \left\{ 1 + \exp \left( \frac{\pi}{2} (1 + u - e^{-u}) \right) \right\} \right) \\
\times f^{(l)} \left( x - \ln \left\{ 1 + \exp \left( \frac{\pi}{2} (1 + u - e^{-u}) \right) \right\} \right) \\
\times \frac{\exp \left( \frac{\pi}{2} (1 + u - e^{-u}) \right) \frac{\pi}{2} (1 + e^{-u})}{1 + \exp \left( \frac{\pi}{2} (1 + u - e^{-u}) \right)} \,du.
\]

(3.17)

Discretizing the integral (3.17) with the trapezoidal rule with step size \( h \) and truncating the infinite sum at \( N^- \) and \( N^+ \) gives

\[
I_i^{(l)}(a_j) \simeq \sum_{k=N^-}^{N^+} g_{l-1}(a_k)f^{(l)}(a_j-a_k)w_k \quad (j = N^-, \ldots, N^+),
\]

(3.18)

where

\[
a_k = \ln \left\{ 1 + \exp \left( \frac{\pi}{2} (1 + k h - e^{-k h}) \right) \right\} \quad \text{and}
\]

\[
w_k = h \frac{\exp \left( \frac{\pi}{2} (1 + k h - e^{-k h}) \right) \frac{\pi}{2} (1 + e^{-k h})}{1 + \exp \left( \frac{\pi}{2} (1 + k h - e^{-k h}) \right)}.
\]

(3.19, 3.20)

Here we chose to evaluate the integral at \( \{a_j\}_{j=1}^{N^+} \) because eq. (2.9) is used recursively and \( g_l(x) \) computed from \( I_i^{(l)}(x) \) is used as the integrand in the next iteration.
Apprently, eq. (3.18) has a form of discrete convolution of a sequence \( \{ g_{t-1}(a_k) \} \) with the Gaussian distribution. This type of discrete convolution can be computed in \( O(N) \) work using the fast Gauss transform [11], where \( N \equiv N^+ - N^- + 1 \) is the number of sample points. Thus we have established the DE-FGT algorithm for lookback options under Merton's model.

**Computational work** Since the computation of eq. (2.9) requires \( l_{\text{max}} + 1 \) fast Gauss transforms and the recursion occurs \( n \) times, the total work for computing the price of a lookback option is \( O(nNl_{\text{max}}) \) (excluding the small amount of work needed to compute eqs. (2.10) and (2.5)). However, Greengard and Strain [11] suggest an extension of the fast Gauss transform which can compute the convolution of a function with sum of multiple Gaussians (or Hermite functions) in only \( O(N) \) work. Using this technique, the total computational work can be reduced to \( O(nN) \). This is smaller than the \( O(nN \log N) \) work needed by Reiner’s method [21], which has been known as the fastest method so far. In addition, when \( N \) increases, the error of the double exponential formula is expected to decrease faster than the error of the Simpson’s rule used in Reiner’s method. Thus we can expect that our method has an advantage over Reiner’s method.

**A note on the form of the change of variables** It would be appropriate here to make some comments on the form of the change of variables defined by eq. (3.16). As can be easily seen, eq. (3.16) approaches the double-exponential transform \( y = \exp(\frac{x}{\tau} \exp(-u)) \) when \( u \to -\infty \) and the linear transform \( y = \frac{x}{2} u \) when \( u \to \infty \). We chose this form because the integrand decays like Gaussian when \( y \to \infty \). In fact, this choice has proved effective in the pricing of various types of path-dependent options including the knock-out options, hindsight options and Bermudan options [8]. However, other types of double-exponential transforms are also applicable and it would be interesting to compare the performance of different transforms.

§4. The DE-FGT algorithm for pricing American lookback options

**Pricing by dynamic programming** In this section, we consider the pricing of American lookback options, for which exercise prior to the maturity \( T \) is permitted. More precisely, we treat a variant for which early exercise is possible only at discrete time points in \([0, T]\) called exercise dates (This type of options are sometimes referred to as Bermudan lookback options). For simplicity, the exercise dates are assumed to coincide with the monitoring dates, though it is
easy to remove this restriction. As the asset price dynamics, we assume the Black-Scholes model or Merton’s jump-diffusion model.

It is well known that the rational price of an American lookback option is given by the following expression:

\[ V_{L^P}^0(S_0) = \sup_{\tau} E_0[ e^{-r\tau} (M_{\tau} - S_{\tau})], \]

where \( \tau \) denotes Markov stopping time [9]. That is, we consider expectation values of the option payoff under all possible stopping times (i.e., exercise strategies) and take the supremum. To find this supremum, we can use dynamic programming and compute the option value backward in time using the recursion [9]:

\[ V_{L^P}^i(S_i, M_i) = \max\{ M_i - S_i, e^{-r\Delta t} E_i[V_{L^P}^{i+1}] \}. \]

Here, \( V_{L^P}^i \) is the option value at time \( t_i \) and is a function of \( M_i \) and \( S_i \) in general and \( E_i[\cdot] \) is the expectation value operator given information up to \( t_i \). 

\( M_i - S_i \) is the profit obtained from exercising the right immediately at time \( t_i \) (the exercise value), while \( e^{-r\Delta t} E_i[V_{L^P}^{i+1}] \) is the discounted expectation value of the option value at the next exercise date (the continuation value). Eq. (4.2) states that it is optimal to exercise the option at time \( t_i \) if the exercise value is greater than the continuation value, and to hold the option otherwise. The initial condition for the recursion (4.2) is given by

\[ V_{L^P}^n(S_n, M_n) = M_n - S_n. \]

**Reduction to a 1-dimensional problem** The main computational task in the pricing of American lookback option is the evaluation of the expectation value in eq. (4.2), which involves two random variables \( S_{i+1} \) and \( M_{i+1} \). To reduce the dimensionality of the problem, we introduce a new variable \( V_{L^P}^i = V_{L^P}^i \) and rewrite the backward recursion formula as follows:

\[ V_{L^P}^i(S_i, M_i) = \max\{ M_i/S_i - 1, e^{-r\Delta t} E_i[V_{L^P}^{i+1}]/S_i \}. \]

By introducing a new measure \( Q' \) defined by

\[ dQ' = \frac{S_{i+1}}{S_i e^{(r-q)(t_{i+1}-t)}} dQ, \]

we have

\[ e^{-r\Delta t} E_i[V_{L^P}^{i+1}] = S_i e^{-q\Delta t} E_i[V_{L^P}^{i+1}/S_{i+1}], \]
where $E'_i[\cdot]$ is the expectation value operator under $Q'$. Inserting this into eq. (4.4) gives

\begin{equation}
(4.7) \quad V'^{LP}_i(S_i, M_i) = \max(M_i/S_i - 1, \ e^{-q\Delta t} E'_i[V'^{LP}_{i+1}]).
\end{equation}

Furthermore, it can be shown by induction that $V'^{LP}_i(S_i, M_i)$ is a function of $M_i/S_i = e^{m_i-s_i}$ only. Denoting this function by $\tilde{V}^{LP}_i$, we finally obtain

\begin{equation}
(4.8) \quad \tilde{V}^{LP}_i(e^{m_i-s_i}) = \max(e^{m_i-s_i} - 1, \ e^{-q\Delta t} E'_i[\tilde{V}^{LP}_{i+1}]).
\end{equation}

Thus we have reached a 1-dimenionial problem, for which the only variable is $m_i - s_i$.

**Computation of the expectation value** To compute the expectation value $E'_i[\tilde{V}^{LP}_{i+1}]$, we need to know the transition probability density function $p(m_{i+1} - s_{i+1}|m_i - s_i)$. Since

\begin{equation}
(4.9) \quad m_{i+1} - s_{i+1} = \max(0, (m_i - s_i) + (s_i - s_{i+1}))
\end{equation}

(See eq. (2.8)), we know that $m_{i+1} - s_{i+1}$ is obtained by adding a random variable $s_i - s_{i+1}$ to $m_i - s_i$ and resetting the result to zero if it is negative. Hence

\begin{equation}
(4.10) \quad p(x|y) = f(x-y)h(x) + \delta(x) \int_{-\infty}^{0} f(x-y) \, dx,
\end{equation}

where $f(x)$ is the probability density function of $s_i - s_{i+1}$ (as defined in section 2) and $h(x)$ is the Heaviside step function which is 1 when $x \geq 0$ and 0 otherwise. Thus the expectation value when $m_i - s_i = y$ can be computed as

\begin{equation}
(4.11) \quad E'_i[\tilde{V}^{LP}_{i+1}] = \int_{-\infty}^{\infty} p(x|y) \tilde{V}^{LP}_{i+1}(e^x) \, dx
= \int_{-\infty}^{0} f(x-y) \, dx \cdot \tilde{V}^{LP}_{i+1}(e^0) + \int_{0}^{\infty} f(x-y) \tilde{V}^{LP}_{i+1}(e^x) \, dx.
\end{equation}

Eqs. (4.8) and (4.11), along with the initial condition

\begin{equation}
(4.12) \quad \tilde{V}^{LP}_n(e^{m_n-s_n}) = e^{m_n-s_n} - 1,
\end{equation}

which follows from eq. (4.3) enable us to compute the option price at time 0 using backward recursion.
Application of the DE-FGT algorithm. Now that we have expressed the option price by a series of convolutions of a function with (a sum of) Gaussian distribution, we can apply our DE-FGT algorithm. However, notice that the function $\tilde{V}_{i+1}^{LP}$, which appears as the integrand in eq. (4.11), is defined using the max operator (see eq. (4.8)) and therefore has discontinuity in its first and higher order derivatives. So straightforward application of the DE formula to eq. (4.11) would not result in the fast convergence rate characteristic of the formula.

To solve this problem, at each time step, we first use the bisection method to find the value $b$ of $m_i - s_i$ at which the exercise value and the continuation value are equal, divide the integration interval in the second term of eq. (4.11) into two subintervals $[0, b]$ and $[b, \infty)$, and apply the DE formula to each of the subinterval. Thus the integrand is smooth in each subinterval and the integration error is expected to decrease rapidly with the number of sample points. Note that this technique cannot be used with Reiner’s method, because it uses a fixed step size $h$ for all time steps (a restriction imposed by the use of FFT), but the length of the subinterval $[0, b]$ is not a multiple of $h$ in general.

The computational work of the DE-FGT algorithm for American lookback options is $O(nN)$ when the number of exercise dates is $n$ and the number of sample points at each date is $N$.

§5. Numerical results

We implemented our DE-FGT algorithms for lookback options and compared its speed and accuracy with that of the conventional methods such as the Monte Carlo method, the binomial method and Reiner’s convolution method [21]. All the numerical experiments were done on a 2.0GHz Pentium IV PC with Red-Hat Linux and GNU C++ compiler.

§5.1. Lookback options under Merton’s model

We show the results for discrete lookback put options under Merton’s model in Figures 1 and 2. The parameters are $S_0 = 100$, $r = 0.1$, $q = 0$, $\sigma = 0.3$, $\lambda = 2.0$, $\delta = 0.3$, $\gamma = 0$, and $T = 0.2$. The number of monitoring dates, $n$, is 25 for Figure 1 and 50 for Figure 2. These frequencies correspond to bi-daily monitoring and daily monitoring, respectively. As the reference prices against which to compute the errors, we used $V_{0}^{LP} = 12.09911864$ for $n = 25$ and $V_{0}^{LP} = 12.57499666$ for $n = 50$, both of which were computed by Reiner’s method with 256,000 sample points.
In the figures, the vertical axis and the horizontal axis represent the error in the calculated option price and the computation time, respectively, both in log scale. In the computation of eq. (3.17), we truncated the integral at the lower bound $u_{\text{min}} = -4.0$ and the upper bound $u_{\text{max}} = 20 \sigma \sqrt{T}$ and used $N$ sample points to approximate the integral. The values of $N$ are shown in the graph. $l_{\text{max}}$ in eq. (3.15) was set to 20. For comparison, we also plotted the computation time and accuracy for the Monte Carlo method and Reiner's method. The number of sample paths for the Monte Carlo method and the number of sample points for Reiner's method are also shown in the graphs. We did not try the binomial method because it takes into account only transitions to adjacent lattice points and is therefore not appropriate for pricing options under jump-diffusion models.

It is clear from the graphs that our DE-FGT algorithm converges much faster than the conventional Monte Carlo method or Reiner's convolution method and can compute the option prices within 1.0 second to an accuracy of $10^{-9}$.

![Figure 1](image_url)

**Figure 1.** Computation time and accuracy of the three algorithms for pricing discrete lookback options under Merton’s model (25 monitoring dates).

§5.2. American lookback options

Results for the American lookback options under the Black-Scholes model are shown in Figures 3 and 4. The parameters are $S_0 = 100$, $r = 0.1$, $q = 0$, $\sigma = 0.25$, and $T = 1$. The graphs show the computation time and accuracy for the Monte Carlo method, Reiner's method, and the DE-FGT algorithm. The number of sample paths and sample points used in each method are also shown in the graphs.
σ = 0.3 and T = 0.2. The number of exercise dates, n, is 5 for Figure 3 and 10 for Figure 4. The reference prices computed by Reiner’s method with 409,600 sample points are \( V_0^{LP} = 7.05538954 \) for \( n = 5 \) and \( V_0^{LP} = 7.92740313 \) for \( n = 10 \).

In this case, we compared three methods, namely, our DE-FGT method, the binomial method [13] and Reiner’s convolution method. We didn’t try the Monte Carlo method because, as is well known, the standard MC method cannot deal with early exercise features. Although several attempts have been made to overcome this difficulty [5][6][17], these methods are basically for options depending on multiple assets and are inherently slower than the binomial method for options on a single asset. In the graphs, the number of sample points for the DE-FGT method and Reiner’s method and the number of time steps for the binomial method are shown.

The results show that Reiner’s method is the fastest when required accuracy is relatively low. Still, our method is competitive when higher accuracy is needed. Also, the convergence of Reiner’s method is rather irregular. This seems to be because of the discontinuity in the first derivative of the integrand.
function, which we mentioned at the end of the previous section. In contrast, our method exhibits much smoother convergence behavior.

![Figure 3](image)

**Figure 3.** Computation time and accuracy of the three algorithms for pricing American lookback options under the BS model (5 exercise dates).

§6. Conclusion

In this paper, we proposed pricing algorithms based on the double-exponential integration formula and the fast Gauss transform for lookback options under Merton’s jump-diffusion model and American lookback options. For lookback options under Merton’s model, our method outperforms conventional methods such as Reiner’s convolution method and can compute the option price within 1 second up to an accuracy of $10^{-9}$. For American lookback options, Reiner’s method is the fastest when required accuracy is relatively low. But our method is competitive when higher accuracy is required. In addition, the convergence of our method is much smoother.

Future work includes extension of our algorithms to more general jump-diffusion asset price models such as the variance gamma models and stochastic volatility models with jumps [10], and extension to other types of exotic options such as options on two or more assets and various types of path-dependent options.
Figure 4. Computation time and accuracy of the three algorithms for pricing American lookback options under the BS model (10 exercise dates).

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Appendix

Theorem 6.1. Suppose that $S_t$ follows the stochastic differential equation (3.1) and we want to compute the expectation value

\begin{equation}
V_0(S_0) = e^{-rT}E[0][h(S_0, S_1, \ldots, S_n) S_n].
\end{equation}

$V_0$ can be computed as

\begin{equation}
V_0(S_0) = e^{-qT}E[0][h(S_0, S_1, \ldots, S_n)],
\end{equation}

where $E[0][\cdot]$ is the expectation value obtained by assuming that $S_t$ follows a modified process specified by eqs. (3.5), (3.6) and (3.7).
Proof. By integrating eq. (3.1) from $t_i$ to $t_{i+1}$, we obtain the relationship between $S_i$ and $S_{i+1}$ as follows:

$$S_i = S_{i-1} \exp \left\{ \left( r - q - \frac{1}{2} \sigma^2 - \nu \lambda \right) \Delta t + \sigma \sqrt{\Delta t} z_0 + \sum_{l=1}^{N_i(\Delta t)} \left( \delta z_l + \gamma - \frac{1}{2} \delta^2 \right) \right\},$$

(6.3)

where $z_l$ ($l = 0, 1, \ldots$) are independent random variables that follow the standard normal distribution $N(0,1)$ under $Q$. Let

$$x_i \equiv \ln \left( \frac{S_i}{S_{i-1}} \right) \quad (i = 1, 2, \ldots, n).$$

Then $x_i$'s are mutually independent and follow the same distribution whose pdf is:

$$p(x_i) = \sum_{l=0}^{\infty} e^{-\lambda \Delta t} \frac{(\lambda \Delta t)^l}{l!} p^{(l)}(x_i),$$

(6.5)

where

$$p^{(l)}(x_i) = \frac{1}{\sqrt{2\pi} \sigma_l} \exp \left\{ -\frac{(x_i - \mu_l)^2}{2\sigma^2_l} \right\},$$

(6.6)

$$\mu_l = \left( r - q - \frac{1}{2} \sigma^2 - \nu \lambda \right) \Delta t + l \left( \gamma - \frac{1}{2} \delta^2 \right), \quad \text{and}$$

$$\sigma^2_l = \sigma^2 \Delta t + l \delta^2.$$  

Using $x_i$, eq. (6.1) can be rewritten as

$$V_0(S_0) = e^{-r T} \int_{-\infty}^{\infty} \ldots \int_{-\infty}^{\infty} dx_1 \ldots dx_n \ h(S_0, S_0 e^{x_1}, \ldots, S_0 e^{x_1+\ldots+x_n}) \ S_0 e^{x_1+\ldots+x_n}$$

$$\times p(x_1) \ldots p(x_n)$$

$$= e^{-r T} S_0 \int_{-\infty}^{\infty} \ldots \int_{-\infty}^{\infty} dx_1 \ldots dx_n \ h(S_0, S_0 e^{x_1}, \ldots, S_0 e^{x_1+\ldots+x_n})$$

$$\times p(x_1)e^{x_1} \ldots p(x_n)e^{x_n}.$$  

(6.9)

From eq. (6.5) through eq. (6.8) we have

\[
p(x_i)e^{x_i} = \sum_{l=0}^{\infty} e^{-\lambda \Delta t} \frac{(\lambda \Delta t)^l}{l!} \frac{1}{\sqrt{2\pi} \sigma_l} \exp \left\{ -\frac{(x_i - \mu_l)^2}{2\sigma^2_l} \right\} e^{x_i}
\]
where we used eqs. (3.3), (3.7) and (3.13). If we define a new function

\[
\tilde{p}(x_i) = \sum_{i=0}^{\infty} e^{-\lambda \Delta t} \frac{(\lambda \Delta t)^i}{i!} \frac{1}{\sqrt{2\pi \sigma_i}} \exp \left\{ -\frac{(x_i - (\mu_i + \sigma_i^2))^2}{2\sigma_i^2} \right\}
\]

we can rewrite eq. (6.9) as

\[
V_0(S_0) = e^{-qT} S_0 \int_{-\infty}^{\infty} dx_1 \cdots \int_{-\infty}^{\infty} dx_n h(S_0, S_0 e^{x_1}, \ldots, S_0 e^{x_1 + \cdots + x_n}) \times \tilde{p}(x_1) \cdots \tilde{p}(x_n)
\]

Noting that \(\tilde{p}(x_i)\) is the probability distribution function of \(x_i\) under the assumption that \(S_t\) follows a modified process specified by eqs. (3.5), (3.6) and (3.7), we can write the right hand side of eq. (6.12) as

\[
e^{-qT} S_0 E_0[h(S_0, S_1, \ldots, S_n)].
\]

This completes the proof. 

References


